

# TITAN GER 1000

5 POWERFULL SYSTEM IN ONE DEVICE

Gold And Metal Detector



.. USER MANUAL ..

**GER DETECT** COMPANY

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# TITAN GER - 1000

5 SYSTEMS

1 DEVICE

3D IMAGING



IONIC SYSTEM



LONG RANGE



MAGNETOMETER

PULSE INDUCTION



# Overview

Dear customer, thank you for choosing TITAN GER – 1000. This device enables you to detect underground gold & Treasures. TITAN GER – 1000 designed to reach 45 meters under the ground and 2500 meters front range. In addition, it contains five systems to confirm your target and identify the target underground.

## Critical Warning

Please be sure that all precautions taken against risks.

Do not use your device while it is raining or on extremely wet floor.

Turn on your device after you make sure that all parts are in place.

Make sure that the device battery is fully charged before searching.

If the battery starts to give a beep sound, close the device and recharge the battery.

Do not start the pulse induction system without connecting the coil cable to the device, otherwise the device will stop in the middle of opening.

It is recommended to read the user manual before starting work on the device to understand everything and to avoid mistakes during the search.

After the device starts making sound and turns off automatically, put the battery on charge and do not try to start the device without charging the battery.

Be aware of high voltage resources, and do not use any charger other than the original charger that comes with the device.

Main unit of the device is under warranty against all electronic breakdowns for two (2) years.

Any damages caused by user errors (opening the main unit, hits, harms etc.) are not within this warranty.

Battery and antenna are also not within this warranty.

You should follow the instructions in this user manual strictly to minimize the faults and to use your device correctly.

## 1 - The Long Range System



This system specializes to cover vast areas and locate the target with in **1** meter Square up to depths of **45** meters below the surface of the ground and Front Range up to **2,500** meters.

### The long range system parts:

Signal Transmitter



Signal Recipient



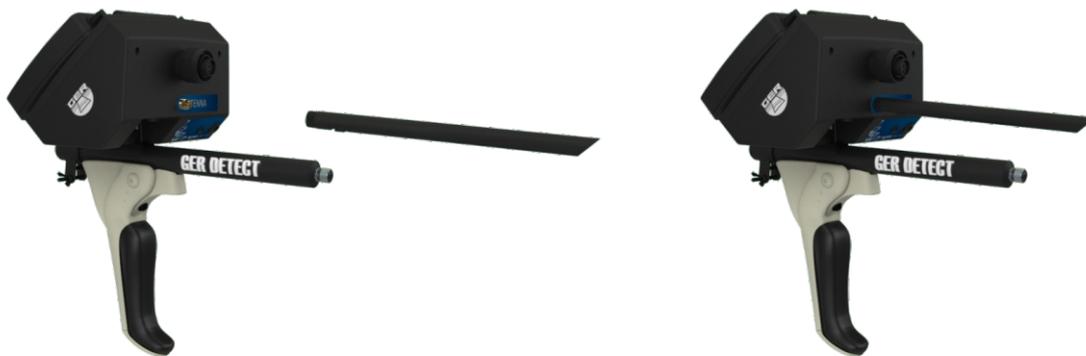
Recipient Antenna



Dispatcher Antenna



## Connect The Dispatcher Antenna



## Connect The Signal Transmitter



## Connect The Signal Recipient



## Connect The Recipient Antenna



# Long Range System : Operation Steps

- Connect The Battery To The Device
- Open The Device Screen And Start The Device Through **ON / OFF** switch



- Click on the screen to display the language list
- The Device work on four languages : **Dautch - English - French - Arabic**



# Long Range System : Operation Steps

- After selecting the language you want to work in ( **English for example** )
- The search system menu will appear
- Select long Range search system



- After Selecting This system, the metals that this system can detect will appear
- Choose the metal to be searched for from a list of metals through pressing on the metal names (**Buried Gold for example**)

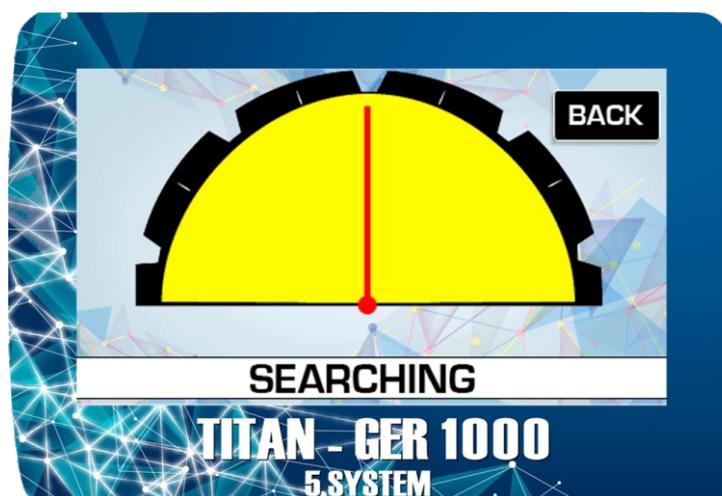


# Long Range System : Operation Steps

- After selecting the metal to be searched for , the front range options will appear
- Choose the front range according to the area you want to reach
- You can select between (0500 M - 1000 M - 1500 M - 2000 M - 2500 M)  
Choose 2500 M for example

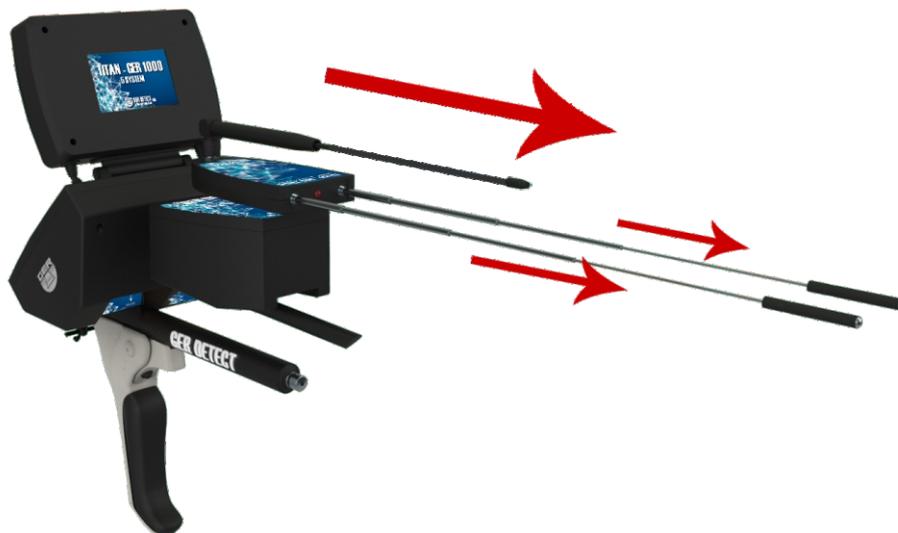


- After selecting the front range , the search screen will appear which contain an indicator , which will guide you directly to the target location
- Make sure that the antenna is pointing ahead
- Adjust the antenna with the indicator on the screen to receive accurate signal



# Long Range System : Operation Steps

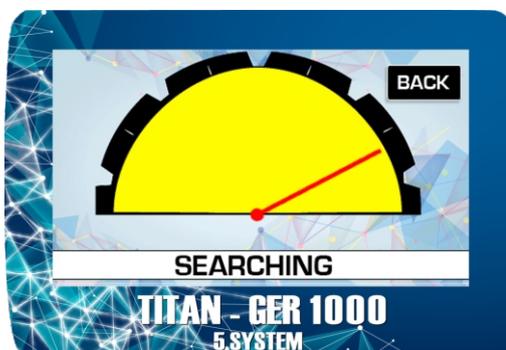
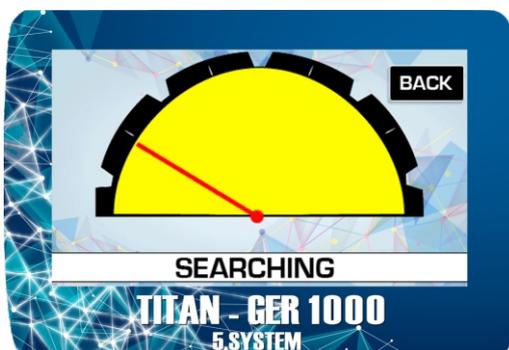
- Increase the length of the signal recipients  
To receive stronger signal even to **2500** meters



Start the search by holding the device as follow :



if the target on the right side the indicator will point to the right side and the same to the left side as follow :



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# Long Range System : Operation Steps



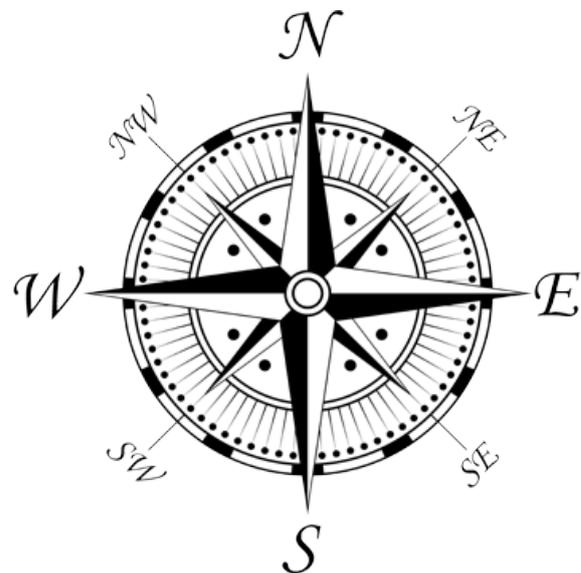
After detecting the target , confirm the target from four directionv

North to South

South to North

East to West

West to East



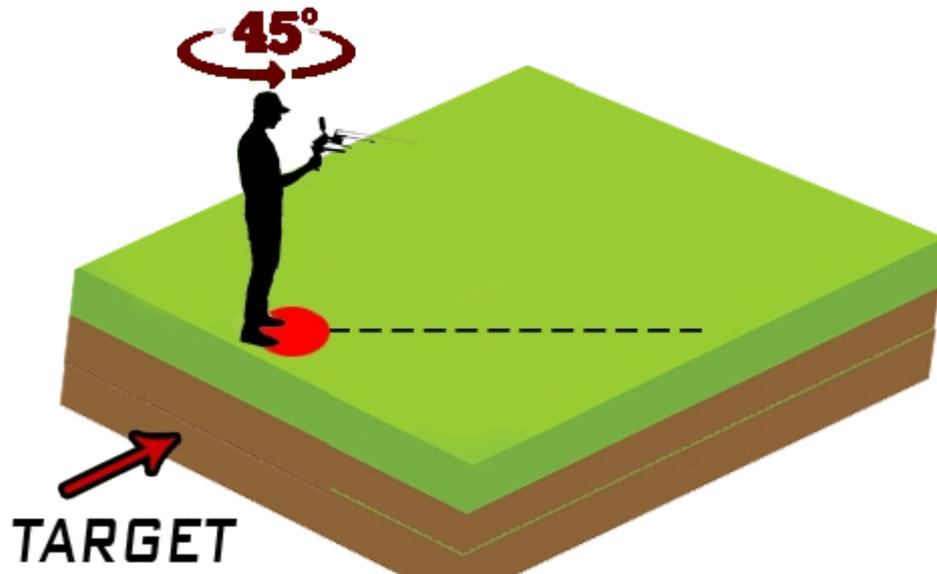
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# Long Range System : Operation Steps

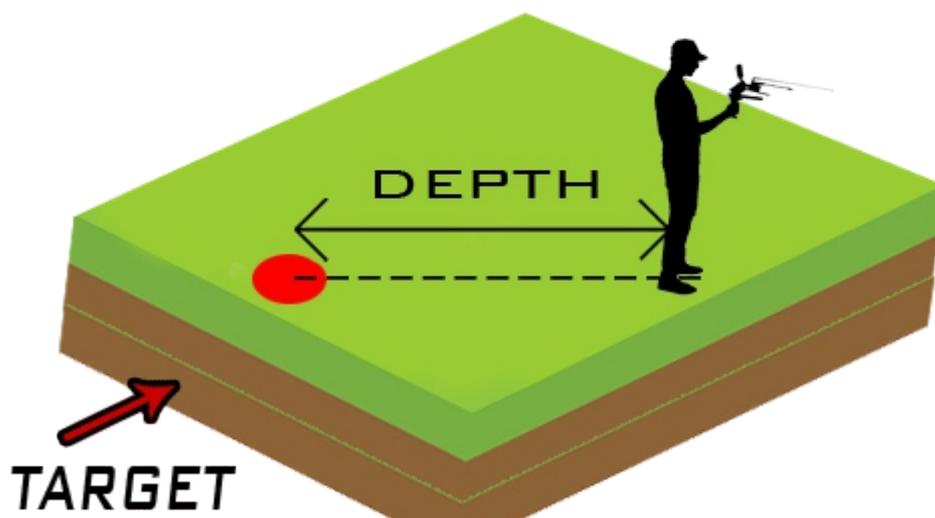
To determine the depth of the discovered target above target and turn 45 degrees  
Walk straight ahead until the antenna reverse to the back



Measure the distance between the antennas reversing back and target center point

The distance between the antennas reversing back and the center point is equal the target depth

For example if the distance is 10 m the depth of the target is 10 m



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## 2 - The Ionic Search System



This system specializes to cover vast areas and locate the target with in **1** meter Square up to depths of **45** meters below the surface of the ground and Front Range up to **500 meters vertical**.

### The Ionic search system parts:

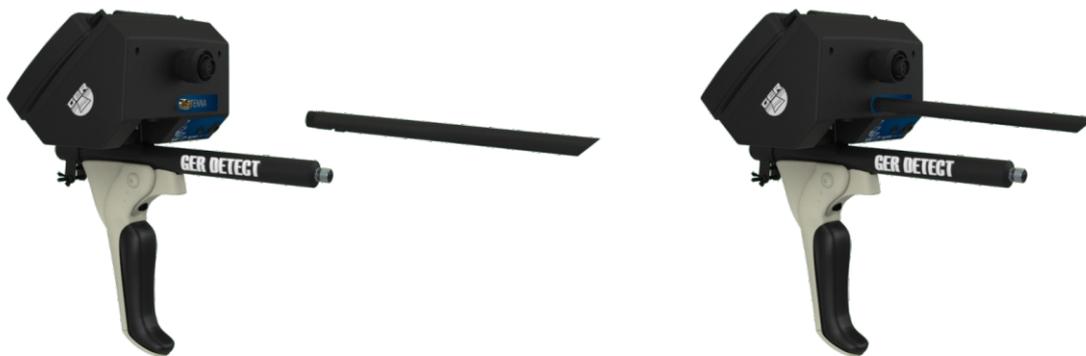
Recipient Antenna



Dispatcher Antenna



## Connect The Dispatcher Antenna



## Connect The Ionic Sensor



# Ionic Search System : Operation Steps

- Connect The Battery To The Device
- Open The Device Screen And Start The Device Through **ON / OFF** switch



- Click on the screen to display the language list
- The Device work on four languages : **Dautch - English - French - Arabic**



# Ionic Search System : Operation Steps

- After selecting the language you want to work in ( **English for example** )
- The search system menu will appear
- Select Ionic search system



- After selecting the ionic system, the search screen will appear.
- Point the device to the ground if the device start to make a sound you must calibrate The device with the ground by pressing on the calibration button as follow



# Ionic Search System : Operation Steps

- After you finish the calibration, start the search by moving the device 180 degrees right and left



When the device detect a target, it will start to make a sound. In addition, the indicator will start to move to alert you that the device find the target.



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# Ionic Search System : Operation Steps

- YOU CAN ALSO USE THE IONIC SEARCH SYSTEM DURING THE DRIVING IN A MOVING VEHICLE... AS FOLLOW:



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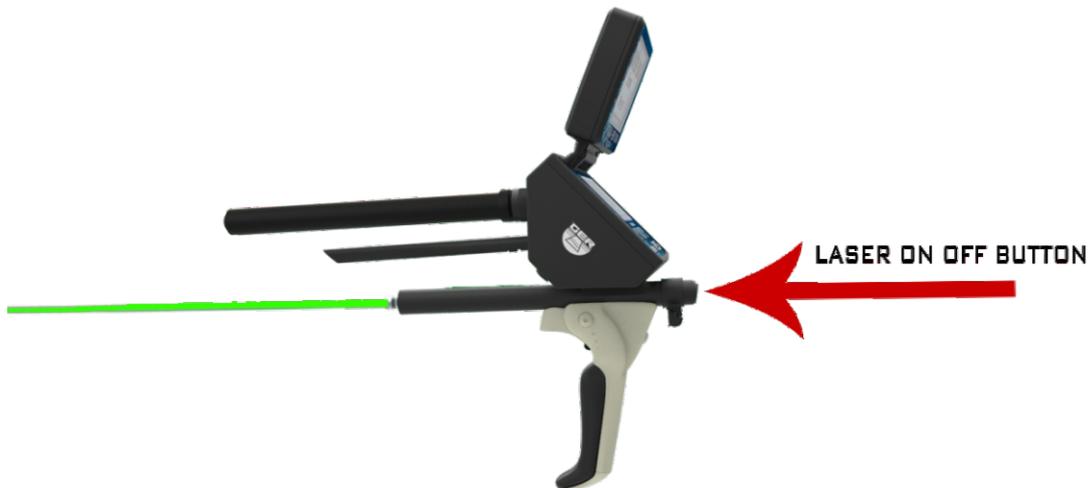
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# Ionic Search System : Operation Steps

In the event of lack of vision, you can turn on the laser to locate the target place by pressing the laser ON OFF, button



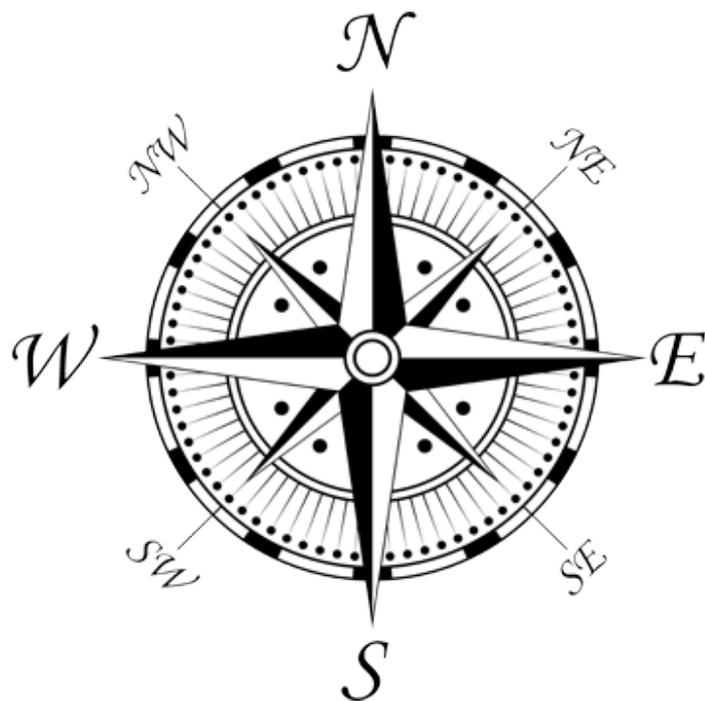
After detecting a target, conform the target from four directions.

NORTH TO SOUTH

SOUTH TO NORTH

EAST TO WEST

WEST TO EAST



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## 3 - 3D Imaging System

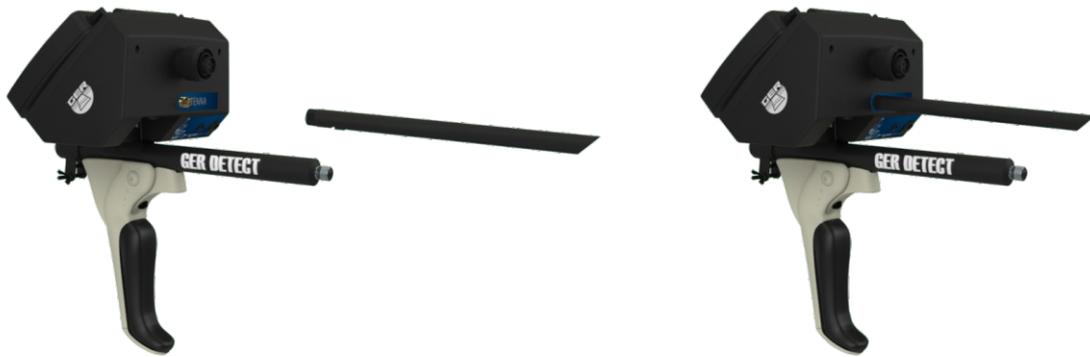


This system specializes to show you the area scanned on the tablet screen in three-dimensional photo and through which you can specify the target size, shape and depth of the target underground up to 45 meters.

## The long range system parts:



## Connect The Dispatcher Antenna



## Connect The 3D Imaging Sensor



# 3D Imaging System : Operation Steps

Install The Tablet Holder To The Device



Fix the tablet that supplied with The device on the tablet holder which contains analysis program to display the photo



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# 3D Imaging System : Operation Steps

Go to the tablet to make a Bluetooth connection between the device and the analysis program.

- Click on the Desktop option



The desktop screen will appear.

- 1- Touch the arrow to reveal the hidden icons.
- 2- Click on the Bluetooth icon.
- 3- Chose add a Bluetooth device.



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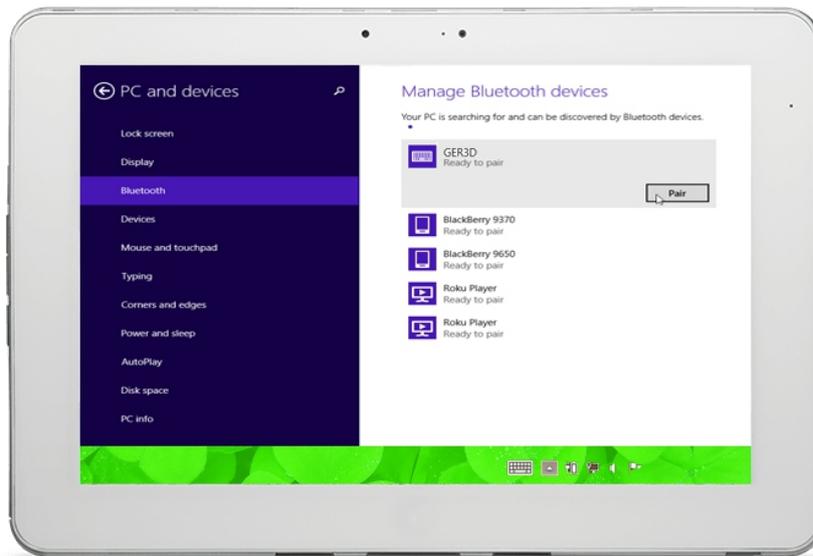
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# 3D Imaging System : Operation Steps

The tablet will start to search for any devices with Bluetooth in the area. When the device name appear click on **pair**.



**NOTE : The Bluetooth Password is : 1000**

Now select the 3D IMAGING system from the systems menu in the device.



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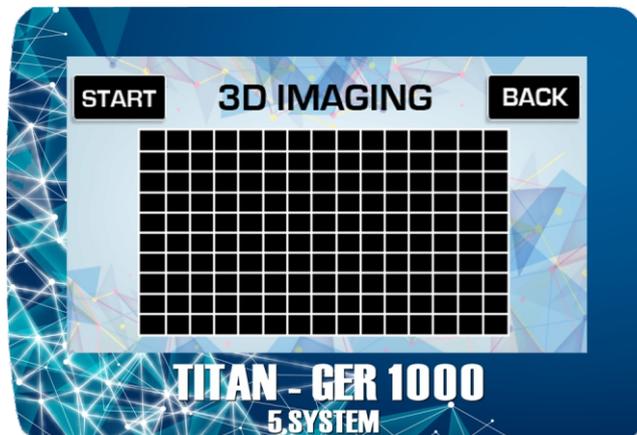
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# 3D Imaging System : Operation Steps

After selecting the 3D imaging system, the search screen will appear.



Open the 3D GER Analyzer that installed on the tablet



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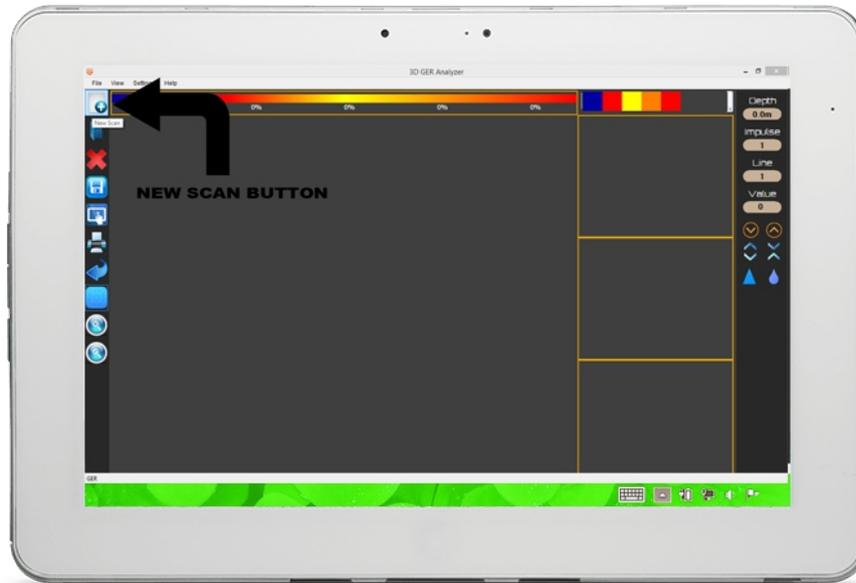
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# 3D Imaging System : Operation Steps

Start a new project to scan the ground by clicking on new scan



THE CONNECTION SETTINGS WINDOW WILL APPEAR ON THE SCREEN.



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# 3D Imaging System : Operation Steps

Enter The Setting as Follow :

- 1- Choose The Device ( Titan Ger )
- 2- Inter Face : Open the bluetooth setting and enter the com number ( Out going ) for example ( com 17 )



- 3- Transmission Method ( Bluetooth )
- 4- Operating Mode ( Ground scan )
- 5- Impulses Per Line 10 to 50 ( each impulse 30 cm )
- 6- Number Of Line 1 to 15 ( each impulse 30 cm )
- 7- Scan Direction ( Optional )

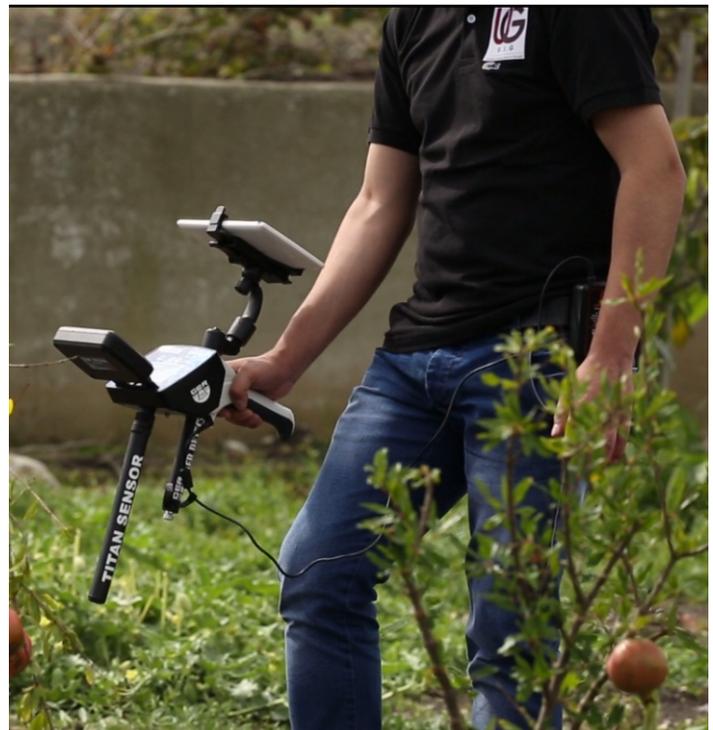


# 3D Imaging System : Operation Steps

After you enter the settings, click on connect and go to the device screen. Therefore, you will start taking pictures as follow:



Hold the device like this...



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## 4 - The MagnetoMeter System



This system specializes to detect magnetic metals (iron) up to depths of 45 meters below the surface of the ground.

The magnetometer system parts:

3D Sensor



## Connect The Sensor To The Device



- Click on the screen to display the language list
- The Device work on four languages : **Dutch - English - French - Arabic**



# Magnetometer System : Operation Steps

- After selecting the language you want to work in ( **English for example** )
- The search system menu will appear
- Select Magnetometer Search system



- After Selecting This system, the search screen will appear
- Point the device to the ground if the device start to make a sound you must calibrate the device with the ground by pressing on the **calibration button** as follow



# Magnetometer System : Operation Steps

- After you finish the calibration , start the search by moving the device forward and back against the ground



When the device detect a target, it will start to make a sound. In addition, the indicator will start to move to alert you that the device find the target.



The sound will start accelirating when the device is close to the target



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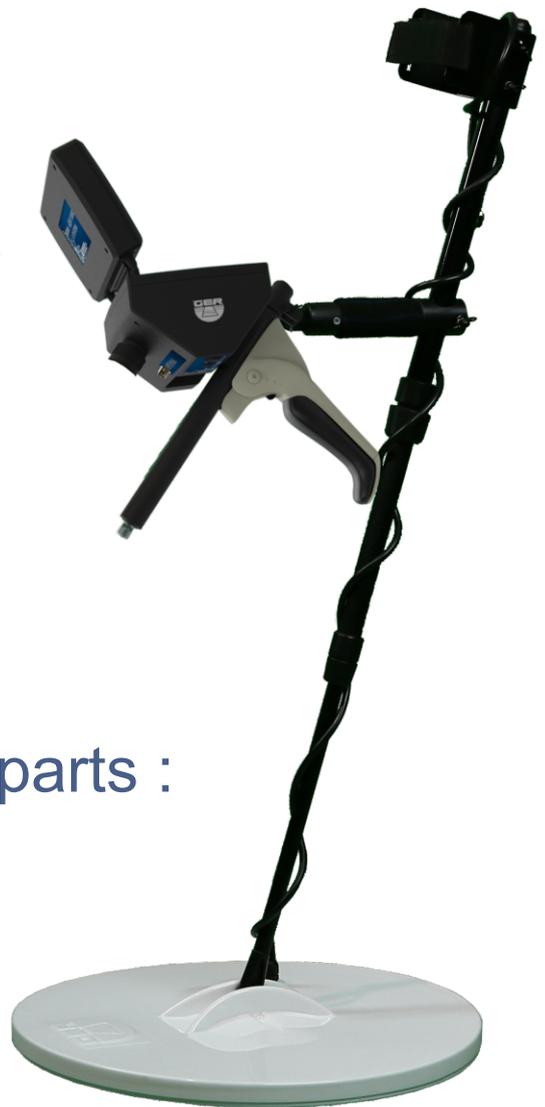
## 5 - The Pulse Indection System

This system specializes to cover the area under the coil directly and locate the target

up to depths of 12 meters below the surface of the ground

This system allow you to discriminate between metals and you can see the target in 3D shapes on the tablet

also you can delete all ferrous metals in addition you can discover the cavities and determine the size and the shape.



### The Pulse induction system parts :

- 1- The main unite
- 2- The coil handle
- 3- 45 X 45 cm search COIL
- 4- 15 X 15 cm search COIL



## Connect The Pulse Indection Parts To The Device

- 1 - Connect The Coil Cable To The Device.
- 2 - Start The Device By Pressing On The Power Switch (on - off)
- 3 - Press on start button under the screen



**Note :** before turning on the device make sure that there is no metal on the person who holding the device or electronic devices or mobile phones or high voltage electricity wires in the place you want to use the device if the device did not complete loading the program that's mean there is metals near the search coil which are affect the operation of the device

To avoid the this problem move the coil or raise it up the grounds a few centimeters and the device will complete the opening process



# Pulse Induction System : Operation Steps

- Select the device language from the list of languages
- Move between languages through the navigation keys (up and down)

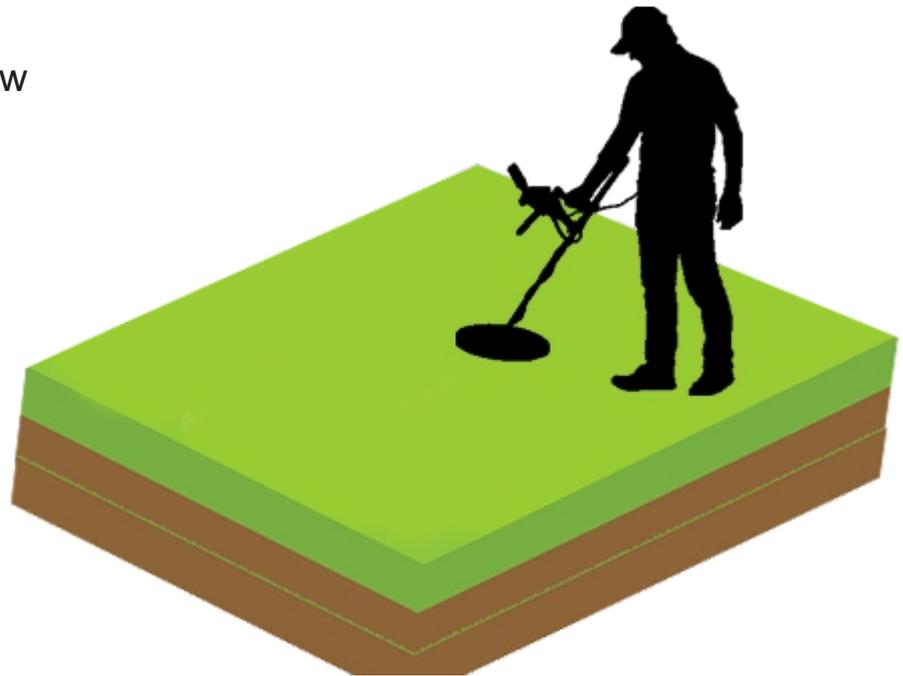


- After selecting the language the device will open to the normal search mode
- First you have to calibrate the device with the ground when the letters **G-B** appear on the screen which means ground Balance
- You can calibrate by pressing the **menu** button.



# Pulse Induction System : Operation Steps

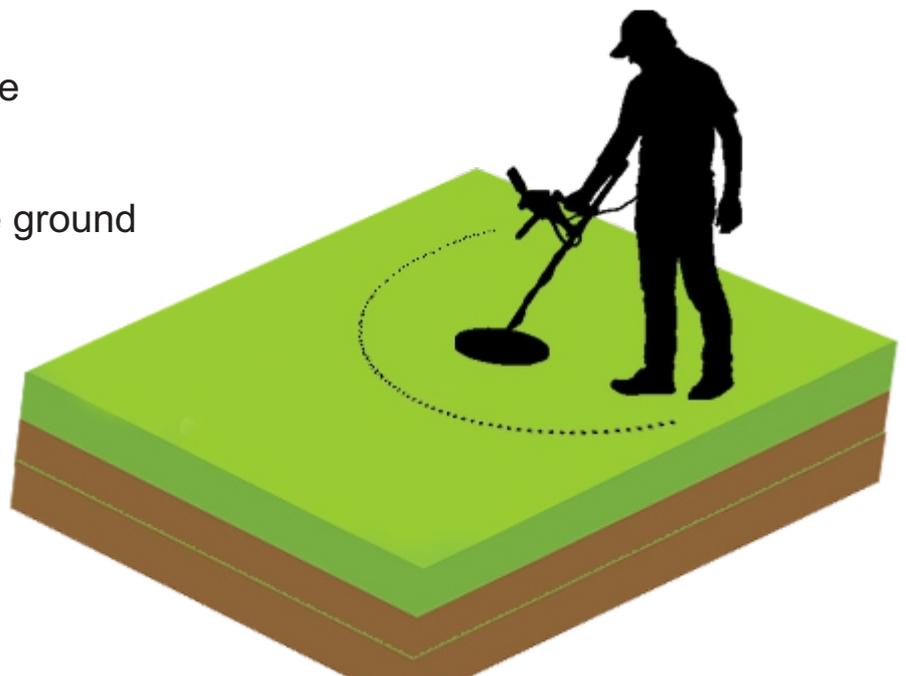
Hold the device as follow  
And start calibration



Start the search by moving the  
device right and left

in stable movement and close  
to the ground.

The coil should be above the ground  
between **5 TO 10 CM**



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# Pulse Indection System : Operation Steps

The device work on three modes

- 1- Normal search mode :  
This mode can detect all kind of metals
- 2- Discrimination search mode :  
This mode can discriminate between ferrous metal and non-ferrous metals
- 3- Cavity search mode :  
This mode can detect all cavities under the ground (Natural cavities – made by human cavities)  
In addition, it can show you the shape and the size

You can adjust the sensitivity by the navigation buttons UP & DOWN.  
The smallest number is the higher sensitivity.

001 = high sensitivity      100 = low sensitivity

Switch between the search modes by pressing on start button.

The device can reach to 12 meters depth under the ground

- 1- 15 X 15 search coil : designed to detect small targets and gold nuggets  
~ This coil can reach 4 meters maximum
- 2- 45 X 45 search coil : designed to detect big targets , treasures , graves ,  
cavities burred gold underground  
~ Tis coil can reach 12 meters maximum

**Note :** The coils depth that we mentioned above don't apply on a new metals  
The metals must be under the ground more than 15 years so the device will  
detect it to 12 meters



# Pulse Indection System : Operation Steps

1- Start with the normal search mode

In case the device detect any metal an indicator will appear on the screen and you will start to hear sound conforming the target is exist



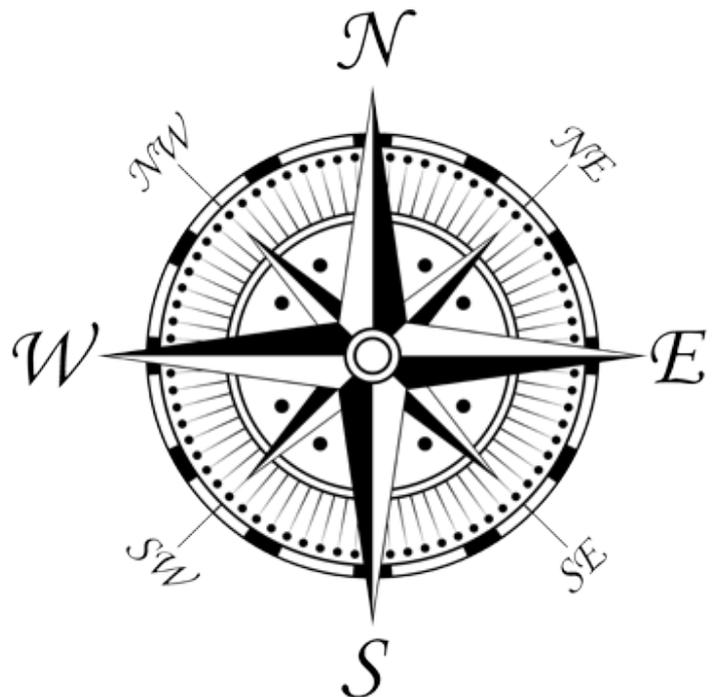
After detecting a target, conform the target from for direction.

NORTH TO SOUTH

SOUTH TO NORTH

EAST TO WEST

WEST TO EAST



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# Pulse Induction System : Operation Steps

2- The discrimination mode : it can Separate between metals as follow



Ferrous for : Iron and its derivatives

Non ferrous for : Gold – silver – bronze – copper–Aluminum – tin .... etc

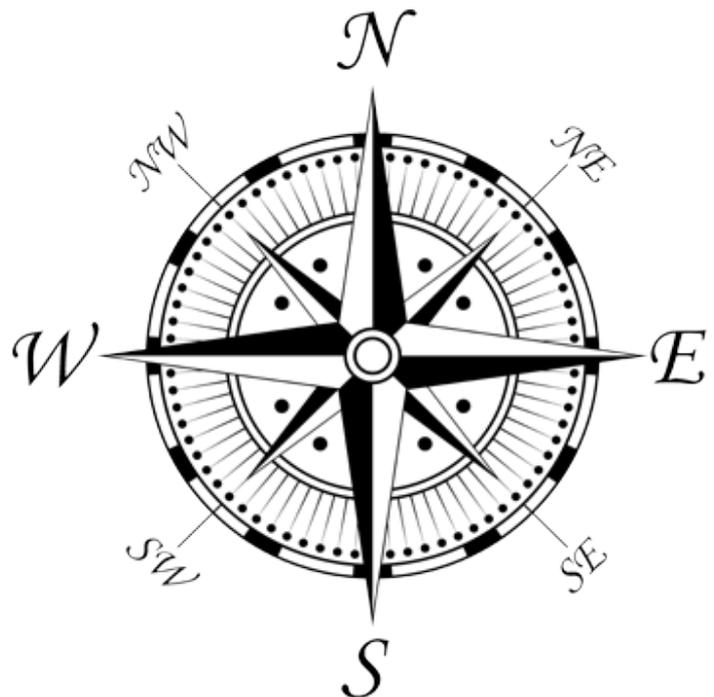
To conform the target type scan the target from four directions

NORTH TO SOUTH

SOUTH TO NORTH

EAST TO WEST

WEST TO EAST



# Pulse Induction System : Operation Steps

In the cavity search mode start your scan in stable motion to determine the shape of the cavity.



..... Thanks for choosing our products .....  
..... We wish you the best of luck in your searching .....



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